# **Monitoring Technique**

**VARIMETER Motor Load Monitor** BH 9097

# **Translation** of the original instructions





- According to IEC/EN 60255-1, IEC/EN 60255-26, DIN/VDE 0435-303
- Identification of
  - Underload P1 and Overload P2
  - Overload P1 (prewarning) and Overload P2 programmable
- Adjustment of P<sub>1</sub> and P<sub>2</sub> on absolute scale
- For motors up to 22 kW / 400 V; 37 kW / 600 V
- Measurement: effective power
- Large current range because of automatic range selection
- 1 changeover contact for P<sub>1</sub> and 1 changeover contact for P<sub>2</sub>
- Adjustable start-up delay ta
- Adjustable switching delay t,
- With automatic or manual reset, programmable
- Test / Reset button for easy setup
- Up to 40 A without external current transformer
- De-energized or energized on fault, programmable
- Also for single-phase operation
- I FD indicators
- Width 45 mm

## **Approvals and Markings**



\* see variants

# **Applications**

The BH 9097 is used to monitor variable loads on industrial motors.

The motor load monitor BH 9097 checks the active power consumption of electrical consumers. As the measuring principle is only single phase correct measurement of 3-phase load is only possible when all three phases have the same load which is normal with motors. Using DIP-switches the unit can be set up to act as under- and overload relay  $P_{\text{1min}}/\,P_{\text{2\,max.}}$  or as overload relay with pre-warning  $P_{\text{1\,max.}}/P_{\text{2\,max.}}$  The settings of P<sub>1</sub> and P<sub>2</sub> are absolute values and calibrated in Watts adjustable via rotational switches. 2 LEDs show the state of the corresponding output relays. The unit can be configured to energise or to de-energise on fault. Every output relay is fitted with it's own time delay t. A start-up delay t acts on both outputs.

## Indication

Green LED, U<sub>N</sub>: During Start-up delay t<sub>a</sub> Flashing:

Continuous: Supply connected

Yellow LED, P1: Flashing: During time delay t<sub>v1</sub> and for set up

assistance

Continuous: When relay P<sub>1</sub> active (contact 11-14) During time delay  $t_{\nu 2}$  and for set up Yellow LED, P2: Flashing:

assistance

When relay P<sub>2</sub> active (contact 21-24)

## **Fault indication**

2 different faults are displayed with the LEDs.

Continuous:

## 1.) No measurement:

Without measuring voltage measurement is not possible - All 3 LEDs flash in sequence one after the other.

The output contacts are in failure state.

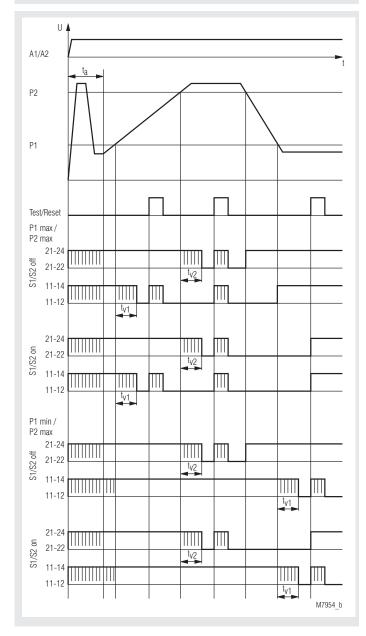
#### 2.) The BH 9097 measures negative load:

Possible reason: The unit measures reverse power or the current

connections are connected wrong.

- All 3 LEDs flash simultaneously.

# Function Diagram for Setting De-energized on Fault\*)



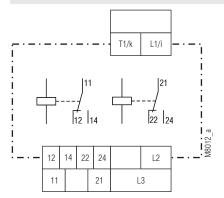
P1max/P2max: Overload monitoring with prewarning P1min/P2max: Under- and overload monitoring

Manual reset S1/S2 ON: S1/S2 OFF: Automatic reset

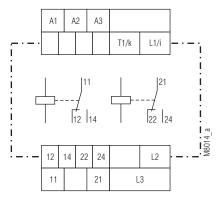
Corresponding LED is flashing

\*) when set to energized on fault the function of LEDs and output relays are inverted.

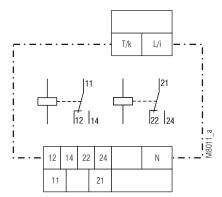
## **Connection Diagrams**



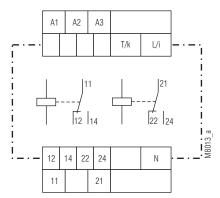
BH 9097.38/001



BH 9097.38/011



BH 9097.38



BH 9097.38/010

#### **Technical Data**

## Input

Measuring voltage

Without auxiliary voltage 0.8 ... 1.1 x U<sub>N</sub> Voltage range:

with auxiliary voltage, see setting ranges

Input resistance: 300 k $\Omega$  ... 500 k $\Omega$ 

Measuring current

Measuring range: See setting ranges

Nominal current [A]	40	24	8	2.4	0.8	0.24
Permissible current range						
(overload) [A] continuously:	0 40	0 40	0 16	08	0 2,4	0 1
1 min. (10 min. break):	150	150	20	16	3	1,5
20 s (10 min. break):	200	200	25	20	4	2
Input res. of current on i-k [m $\Omega$ ]:	≤ 1	≤ 1	7	14	830	830

10 ... 400 Hz Frequency range:

(please see characteristics M7953)

### **Setting Ranges**

# P<sub>1</sub> und P<sub>2</sub> on absolute scale

Switch

load range for P1 and P2:

Lower range Upper range

Measuring accuracy (in % of setting value):

 $\pm$  4 % (2 % on request)

Hysteresis

(in % of setting value): < 5 % < 40 % Harmonic distortion: < 50 ms

Reaction time: Switching delay t<sub>v1</sub>/t<sub>v2</sub>: Start-up delay t<sub>a</sub>:

0 ... 10 s (infinite variable) 0 ... 30 s (infinite variable)

## **Setting Ranges**

Available variants	Measuring voltage U <sub>N</sub>	Measuring current I <sub>N</sub> [A]	selection of load range
1-phase	to an		
without auxiliary vol	liage		
BH 9097.38/000	AC 230 V	0.0024 0.24	0.1 60 W
	AC 230 V	0.024 2.4	1 600 W
	AC 230 V	0.24 24	10 6000 W
with auxiliary voltag	e		
BH 9097.38/010	AC 35250 V	0.0024 0,24	0.1 60 W
	AC 35250 V	0.024 2,4	1 600 W
	AC 35250 V	0.24 24	10 6000 W
3-phase			
without auxiliary vol	tage		
BH 9097.38/001	3 AC 400 V	8,0 800.0	0.1 60 W
	3 AC 400 V	0.08 8	10 6000 W
	3 AC 400 V	0.4 40	0.1 30 kW
with auxiliary voltag	ie		
BH 9097.38/011	3 AC 60 440 V	8,0 800.0	1 600 W
	3 AC 60 440 V	0.08 8	10 6000 W
	3 AC 100 760 V	0.4 40	0.1 52 kW

## **Auxiliary Circuit**

Auxiliary voltage U<sub>H</sub>

Only for BH 9097.38/010,

BH 9097.38/011: AC 110 V (Klemmen A 1 - A 2),

AC 230 V (Klemmen A 1 - A 3),

DC 24 V 0.8 ... 1.1 U<sub>H</sub>

Voltage range: Frequency range of U<sub>1</sub>:

45 ... 400 Hz

Input current

AC 110 V: Approx. 30 mA AC 230 V: Approx. 15 mA DC 24 V: Approx.. 50 mA

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#### **Technical Data**

#### Output

Contacts: 1 changeover contact for P1 1 changeover contact for P2

Thermal current I,: 2 x 5 A

Switching capacity

To AC 15

NO contact: 3 A / AC 230 V IEC/EN 60947-5-1 IEC/EN 60947-5-1 NC contact: 1 A / AC 230 V To DC 13: 1 A / DC 24 V IEC/EN 60947-5-1

2x105 switching cycles IEC/EN 60947-5-1

1800 switching cycles / h

**Electrical life** 

To AC 15 at 3 A, AC 230 V:

Permissible switching

frequency: Short circuit strength

max. fuse rating:

IEC/EN 60947-5-1 4 A gG / gL Mechanical life: 30 x 106 switching cycles

### **General Data**

Operating mode: Continuous Temperature range: - 20 ... + 55°C Clearance and creepage

distances

Rated impulse voltage /

pollution degree: 4 kV / 2 IEC 60664-1 **EMC** IEC/EN 61000-4-2

Electrostatic discharge: 8 kV (air) HF-irradiation: 10 V / m IEC/EN 61000-4-3 Fast transients: 2 kV IEC/EN 61000-4-4

Surge voltages Between

wires for power supply: 1 kV IEC/EN 61000-4-5 Between wire and ground: 2 kV IEC/EN 61000-4-5 HF-wire guided: 10 V IEC/EN 61000-4-6 Interference suppression: Limit value class B EN 55011

IP 40 Housing: IEC/EN 60529 IP 20 Terminals: IEC/EN 60529 Housing: Thermoplastic with V0 behaviour according to UL subject 94

Vibration resistance: Amplitude 0,35 mm

frequency 10 ... 55 Hz IEC/EN 60068-2-6 20 / 055 / 04 Climate resistance: IEC/EN 60068-1 EN 50005

Terminal designation: Wire connection

Degree of protection

1 x 10 mm<sup>2</sup> solid or Load terminals:

1 x 6 mm<sup>2</sup> stranded wire with sleeve

Control terminals: 1 x 4 mm2 solid or 2 x 1.5 mm<sup>2</sup> stranded wire with sleeve

1 x 2,5 mm<sup>2</sup> stranded wire with sleeve

DIN 46228-1/-2/-3/-4

Box terminals with self-lifting wire Wire fixing:

protection and Plus-minus terminal

screws M3.5

Mounting: DIN rail IEC/EN 60715 Weight: 430 g

**Dimensions** 

Width x height x depth: 45 x 84 x 121 mm

# **CCC-Data**

Thermal current I<sub>th</sub>: 4 A

**Switching capacity** 

3 A / AC 230 V IEC/EN 60947-5-1 To AC 15: To DC 13: 1 A / DC 24 V IEC/EN 60947-5-1



Technical data that is not stated in the CCC-Data, can be found in the technical data section.

#### **Standard Type**

BH 9097.38/001 3 AC 400 V 50 / 60 Hz  $t_a$  30 s  $t_v$  10 s

Article number: 0053944

3-phase, without auxiliary supply

changeover contact for P1 and Output:

1 changeover contact for P2

Nominal voltage U<sub>N</sub>: 3 AC 400 V Width: 45 mm

#### **Variants**

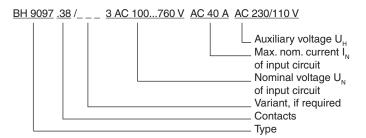
With CCC-approval on request BH 9097: BH 9097.38/001: 3-phase without auxiliary supply 3-phase with auxiliary supply BH 9097.38/011: BH 9097.38/000: 1-phase without auxiliary supply BH 9097.38/010: 1-phase with auxiliary supply BH 9097.38/1\_ \_:

With galvanically separated current path. For applications with current transformers

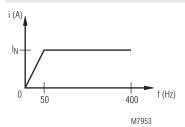
grounded on the secondary side, current range limited to 25 A Same as BH 9097.38/001, but with

BH 9097.38/801: start up delay t<sub>a</sub> = 0 ... 10 s

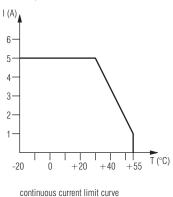
#### Ordering example for variants



#### Characteristics



Max. input current curve in relation to input frequency



(current over 2 contacts) M8367

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#### **Settings**

 $\begin{array}{lll} \text{2 rotational switches for P}_1\text{:} & \text{Value P}_1\text{ (2 decades)} \\ \text{2 rotational switches for P}_2\text{:} & \text{Value P}_2\text{ (2 decades)} \\ \text{Potentiometer t}_{v_2}\text{:} & \text{Time delay for value P}_1\\ \text{Time delay for value P}_2\text{:} & \text{Time delay for value P}_2\\ \end{array}$ 

Potentiometer t<sub>a</sub>: Start-up delay after connection voltage Test/Reset-Taste: Test function as setting assistance

Reset function when manual reset is

selected

Dip-switches:

x10 | x1 A | B

Selection of upper / lower load range Selection of closed or open circuit

Operation for output relays

P<sub>2 max.</sub> | P<sub>2 max.</sub> P<sub>1 max.</sub> | P<sub>1 min.</sub>

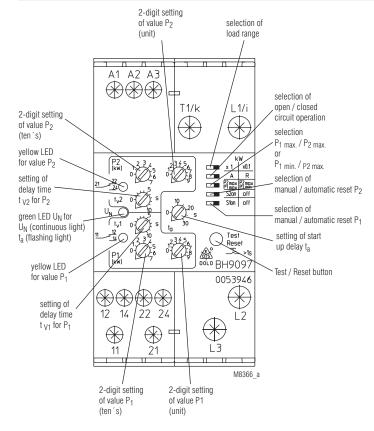
2 MAX switching values (Overload with Pre-warning) or MAX and MIN switching value (Overload / Underload monitoring)

S1 ON I OFF: Manual / automatic reset for P<sub>1</sub> S2 ON I OFF: Manual / automatic reset for P<sub>2</sub>

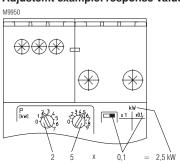
#### Connection

The device has to be connected according to the connection diagrams. The motor is connected to terminals L/i and T/k or L1/i and T1/k. The flow direction of the current has to be observed. On reverse power the unit gives a fault signal. The max continuous motor current is 40 A limited by the terminals. With higher currents a current transformer with 2,5 VA has to be used.

#### **Set-up Procedure and Setting Instructions**



## Adjustemt example: response value: 2,5 kW



Response value =  $25 \times 0.1 = 2.5 \text{ kW}$ 

The adjustment of the unit can be made without additional measuring equipment and calculations. Please make sure that the load values are in the permitted operating range of the unit. Based on the max permitted values the BH 9097 can be used for 48 kW 3-phase motors at 3 AC 690 V and 5.8 kW single phase motors at AC 230 V.

There are three methods to set up the unit:

### Method 1:

If the absolute values of the actual required tripping points  $P_1$  and  $P_2$  are known, they can be set directly on the unit (2-digit setting of  $P_1$  and  $P_2$ ).

#### Method 2:

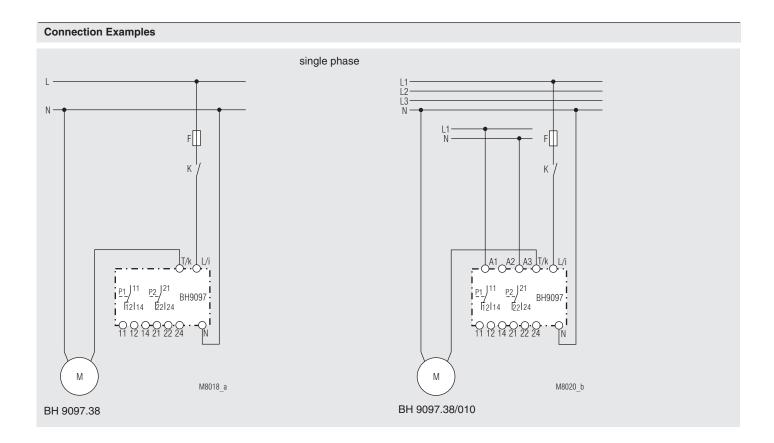
This method is recommended when it is possible to simulate the different load situations during set-up. In this case nothing has to be calculated. Turn the delay time for  $\mathsf{P}_1$  and  $\mathsf{P}_2$  to min. The motor runs in underload while the Pot 1 is turned until the output relay switches. The same has to be done for overload. Now the unit is set accurately. Now adjust the operate delay and the start-up delay to the required values.

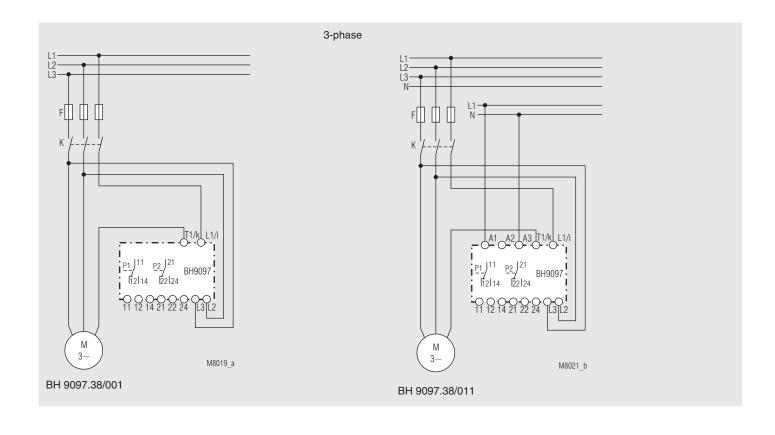
Pressing the test / reset button during setup disables the switching of the output relays. The LEDs of P, and P, flash.

### Method 3:

This method is the most simple one but not the most accurate. The operate delay is set to min. The motor is switched on and runs on nominal load. With both potentiometers the set points are searched by slowly turning the max. Pot from high to low value and the min. Pot from low to high value until the corresponding output relays switch. After that turn the Pot  $\rm P_2$  to the right (e.g. + 10 %) side and the Pot  $\rm P_1$  to the left (e.g. - 10 %) until the output relays reset. The unit is now set and responds if the load differs from the nominal value. Finally set the operate delay and start-up delay to the required values. The DIP switch should be set to  $\rm P_{1\,min}$  /  $\rm P_{2\,max}$ .

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## **Connection Examples with External Current Transformer**

